

The Optimal Regularization and its Application in Extreme Learning Machine for Regression Analysis and Multiclass Classification

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Basic Theory of Extreme Learning Machine (ELM)

ELM is a newly developed single layer feedforward neural network (SLFN), proposed by Huang (2006). The model of ELM can be described as:

$$\mathbf{H}_{N \times L} \mathbf{\beta}_{L \times m} = \mathbf{Y}_{N \times m} \quad \text{with} \quad \mathbf{\beta} = \begin{bmatrix} \mathbf{\beta}_{1}^{T} \\ \mathbf{M} \\ \mathbf{\beta}_{L}^{T} \end{bmatrix}_{L \times m}, \quad \mathbf{Y} = \begin{bmatrix} \mathbf{y}_{1}^{T} \\ \mathbf{M} \\ \mathbf{y}_{N}^{T} \end{bmatrix}_{N \times m}$$

Where Y is the output matrix (vector), β is the connecting matrix between hidden layer and output layer, H is the hidden layer matrix (feature mapping matrix).

$$\mathbf{H} = \begin{bmatrix} g(\mathbf{w}_1 \cdot \mathbf{x}_1 + b_{11}) & \mathbf{L} & g(\mathbf{w}_L \cdot \mathbf{x}_1 + b_{1L}) \\ \mathbf{M} & \mathbf{O} & \mathbf{M} \\ g(\mathbf{w}_1 \cdot \mathbf{x}_N + b_{N1}) & \mathbf{L} & g(\mathbf{w}_L \cdot \mathbf{x}_N + b_{NL}) \end{bmatrix}_{N \times L}$$

- w connecting matrix between input layer and hidden layer
- **x** input matrix
- **b** bias matrix

The estimated solution of $\boldsymbol{\beta}$ based on least squares estimation is

$$\beta = H^+Y$$

 H^+ is the Moore-Penrose generalized inverse of the feature mapping matrix H.



ELM has fast training speed and shows high accuracy. But there exists two main problems for ELM.

1. Using Moore-Penrose generalized inverse to estimate the solution of $\hat{\beta}$ tend to generate an over-fitting model

$L(\mathbf{H}, \mathbf{Y}; \boldsymbol{\beta}) = P\mathbf{H}\boldsymbol{\beta} - \mathbf{Y}P^2 = \min$

2. Instability of solution of $\hat{\boldsymbol{\beta}}$ because of ill-pose in normal matrix $\mathbf{N} = \mathbf{H}^{T}\mathbf{H}$

In order to improve generalization performance and stability of ELM, regularization is brought in to penalizes the coefficients of weight matrix $\hat{\beta}$. The model of ELM with regularization is as follows:

$$L(\mathbf{H}, \mathbf{Y}; \boldsymbol{\beta}, \boldsymbol{\lambda}) = \mathbf{P}\mathbf{H}\boldsymbol{\beta} - \mathbf{Y}\,\mathbf{P}^2 + \boldsymbol{\lambda}\,\mathbf{P}\boldsymbol{\beta}\,\mathbf{P}^2 \tag{1}$$

In such case, the solution of $\hat{\beta}$ can be described as:

$$\hat{\boldsymbol{\beta}} = \mathbf{H}^T (\mathbf{H}\mathbf{H}^T + \lambda \mathbf{I})^{-1} \mathbf{Y}$$
(2)

or
$$\hat{\boldsymbol{\beta}} = (\mathbf{H}^T \mathbf{H} + \lambda \mathbf{I})^{-1} \mathbf{H}^T \mathbf{Y}$$
(3)



How to choose the expression of $\hat{\beta}$

- a) Number of training samples N < number of hidden layer nodes L, equation (2) is chosen
- b) Number of training samples N > number of hidden layer nodes L, equation (3) is chosen

In normal cases, we have sufficient training samples, so that we choose equation (3) as the solution of $\hat{\beta}$. But how to choose an optimal regularization parameter λ is still a problem.

Deng (2009) has proposed a heuristic method.

 $\lambda = [2^{-50}, 2^{-49}, L 0, L , 2^{49}, 2^{50}]$

Cross-validation is used to choose a regularization parameter with minimum RMSE for validation set.



A-optimal design regularization

Cai (2004) proposed A-optimal design regularization. With A-optimal design regularization, the regularization parameter is determined by the minimum trace of mean square error (MSE) of $\hat{\beta}$.

$$MSE\{\beta\} := E\{(\beta-\beta)(\beta-\beta)'\} = E\|\beta-\beta\|^{2}$$

$$= E[(\beta-\beta+\beta) + (E\beta-\beta)]'[(\beta-\beta+\beta)] + (E\beta-\beta)]'$$

$$= E[(\beta-\beta)'(\beta-\beta+\beta)] + [(E\beta-\beta)][+(E\beta-\beta)]'$$

$$= Cov\{\beta\} + BB'$$

$$(4)$$

Where $Cov(\hat{\beta})$ is Variance-Covariance matrix

$$\operatorname{Cov}(\hat{\boldsymbol{\beta}}) = (\mathbf{H}^T \mathbf{H} + \lambda \mathbf{I})^{-1} \mathbf{H}^T \mathbf{H} (\mathbf{H}^T \mathbf{H} + \lambda \mathbf{I})^{-1}$$
(5)

and **B** is bias vector (matrix).

S

$$\mathbf{B} = E(\hat{\boldsymbol{\beta}} - \boldsymbol{\beta})$$

=-[**I**-(**H**^T**H** + \lambda **I**)⁻¹**H**^T**H**]\blackbd{\blackbd{\blackbd{\beta}}}
=\lambda(**H**^T**H** + \lambda **I**)⁻¹**I**\blackbd{\blackbd{\blackbd{\beta}}} (6)



Then we can calculate $MSE(\widehat{\boldsymbol{\beta}})$

$MSE(\beta) = (\mathbf{H}^{\mathrm{T}}\mathbf{H} + \lambda \mathbf{I})^{-1}[\mathbf{H}^{\mathrm{T}}\mathbf{H} + (\lambda \mathbf{I})\beta\beta'(\lambda \mathbf{I})](\mathbf{H}^{\mathrm{T}}\mathbf{H} + \lambda \mathbf{I})^{-1}$ (7)

The regularization parameter λ follows by A-optimal design in the sense of trace(MSE) = min if and only if

$$= \frac{\text{trace}(\mathbf{H}^{\mathrm{T}}\mathbf{H}(\mathbf{H}^{\mathrm{T}}\mathbf{H} + \mathbf{A})^{-3})}{\boldsymbol{\beta}'(\mathbf{H}^{\mathrm{T}}\mathbf{H} + \mathbf{A})^{-2}\mathbf{H}^{\mathrm{T}}\mathbf{H}(\mathbf{H}^{\mathrm{T}}\mathbf{H} + \mathbf{A})^{-1}\boldsymbol{\beta}}$$
(8)

The performance of ELM with A-optimal design regularization will be evaluated on 3 case studies.

Simulated Case: Approximation of "Sine Function"

Simulation 1 (without outliers):

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Dataset: 10000 samples uniformly distributed in (-10, 10) of sine function Training data: 5000 samples with random noise distributed in (-0.2, 0.2)Testing data: other 5000 noise-free samples

| Simulation without outliers | | | | | | |
|-----------------------------|--------|--------|--|--|--|--|
| ELM RELM | | | | | | |
| RMSE (training data) | 0.1150 | 0.1157 | | | | |
| RMSE (testing data) | 0.0145 | 0.0151 | | | | |

Simulation 2 (with outliers):

Dataset: 9900 samples uniformly distributed in (-10,10) of sine function

Training data: 4900 samples with random noise distributed in (-0.2, 0.2) and 100 outliers distributed in

(-2, 2)

Testing data: other 5000 noise-free samples

| Simulation with outliers | | | | | | |
|--------------------------|--------|--------|--|--|--|--|
| ELM RELM | | | | | | |
| RMSE (training data) | 0.2566 | 0.2405 | | | | |
| RMSE (testing data) | 0.1006 | 0.0524 | | | | |





Approximation by ELM without outliers



Approximation by RELM without outliers





Approximation by ELM with outliers

Approximation by RELM with outliers

1

0.

-0.5

-1.5

10

training sample

exact Approximation



Real-World Regression Analysis

Data source:

http://www.liaad.up.pt/~ltorgo/Regression/DataSets.html

An example of datasets: Bank domains

- Synthetically generated data from a simulation of how bank-customers choose their banks.
- > 32 numerical features as input and 1 numerical decision as output
- ➢ 8192 samples, 4500 for training and 3692 for testing

| Datasets | Training data | Testing data | Feature |
|-----------------------|---------------|--------------|---------|
| Bank domains | 4500 | 3692 | 32 |
| Puma | 4499 | 3693 | 32 |
| Triazines | 124 | 62 | 60 |
| Pyrim | 49 | 25 | 27 |
| Machine CPU | 139 | 70 | 6 |
| Kinematic | 5461 | 2731 | 8 |
| California housing | 13760 | 6880 | 8 |
| Stocks domain | 633 | 317 | 9 |
| Fried_delve | 27179 | 13589 | 10 |



Testing results: comparison of RMSE between ELM and RELM

| | RMSE | | | | |
|--------------------|---------------|--------|--------------|--------|--|
| Dataset | Training data | | Testing data | | |
| | ELM | RELM | ELM | RELM | |
| Bank domains | 0.0795 | 0.0806 | 0.0901 | 0.0819 | |
| Puma | 0.0245 | 0.0248 | 0.0296 | 0.0251 | |
| Triazines | 0.1479 | 0.1494 | 0.1661 | 0.1391 | |
| Pyrim | 0.0776 | 0.0780 | 0.1004 | 0.0876 | |
| Machine CPU | 0.0461 | 0.0506 | 0.0594 | 0.0511 | |
| Kinematic | 0.0891 | 0.0903 | 0.1021 | 0.0968 | |
| California housing | 0.1221 | 0.1246 | 0.1256 | 0.1251 | |
| Stocks domain | 0.0297 | 0.0311 | 0.0396 | 0.0316 | |
| Fried_delve | 0.1976 | 0.2011 | 0.3169 | 0.2466 | |



Image Multiclass Classification

Data source: https://glovis.usgs.gov/ Study area: a part of Wuhan, China Data: Landsat 8 satellite image Resolution of image: 30m × 30m Image size: 598 × 597 pixels Feature: 7 spectral bands 5 classes: grass, tree, bare land, building, water 3550 labeled pixels as samples.

| Number of labeled pixels for each class | | | | | |
|---|-------|------|-----------|-------|-------|
| building | grass | tree | bare land | water | total |
| 750 | 569 | 512 | 989 | 730 | 3550 |

Training data: Each class: 100 randomly chosen pixels Testing data: Other 3050 pixels.









Konfusionsmatrix

Class from reference data

C

Original ELM:

Class from

| - | | Water | Bare land | Tree | Grass | Building |
|------|-----------|-------|-----------|------|-------|----------|
| 101 | Water | 730 | 0 | 0 | 0 | 0 |
| Ical | Bare land | 80 | 890 | 1 | 7 | 11 |
| SIII | Tree | 31 | 2 | 156 | 323 | 0 |
| las | Grass | 0 | 0 | 0 | 569 | 0 |
| 0 | Building | 31 | 7 | 0 | 0 | 712 |

| A-optimal design |
|------------------|
| regularized ELM: |

| | Class from reference data | | | | | |
|-------------|---------------------------|-------|-----------|------|-------|----------|
| - | | Water | Bare land | Tree | Grass | Building |
| tion | Water | 730 | 0 | 0 | 0 | 0 |
| fro | Bare land | 35 | 941 | 2 | 5 | 6 |
| ass sifi | Tree | 7 | 14 | 384 | 107 | 0 |
| Clas | Grass | 0 | 0 | 1 | 568 | 0 |
| 0 | Building | 13 | 7 | 0 | 7 | 723 |

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| | Accuracy | Cohens kappa coefficient (κ) |
|-----------------|----------|------------------------------|
| Original ELM | 84.11% | 0.7596 |
| Regularized ELM | 93.16% | 0.9189 |

 $accuracy = \frac{number of correct pixels}{number of total pixels}$

 $\kappa = \frac{p_0 - p_c}{1 - p_c}$ with p_0 – the relative observed agreement

$$p_0 = \frac{1}{N} \sum_i K_{ii}$$

N – sum of elements in the konfusionsmatrix p_c – the hypothetical probability of chance agreement $p_c = \frac{1}{N^2} \sum_i (\sum_j K_{ji} \cdot K_{ij})$



Original ELM

A-optimal design regularized ELM





Conclusion

- With A-optimal design regularization, the robustness of ELM is obviously improved. 1.
- Overfitting model can be effectively avoided in training process, so that generalization 2. performance can be advanced.
- In image classification, A-optimal design regularization helps original ELM to improve the 3. accuracy of classification.

Outlook

- Apply the A-optimal design regularization in multi-hidden-layer neural networks.
- Try to solve other regularization problems in machine learning, e.g. for Support Vector Machine 2. (SVM).
- Study the prospect of A-optimal design regularization in deep learning, e.g. for convolutional 3. neural networks (CNNs).



Thank you

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